

Code Pi	roject	Release			
ST06 A	40-B	Α	TECHNICAL DATASHEET		
		MAG	NETIC SENSOR MTV I		
GENERAL CHAR	ACTERIS	TICS			
alignment tolerances. Small size, to allow insta	0 DPI. st mounting of t allation in narrow	he entire mea v spaces.	asuring system, with wide		
	stoferrite is supplied in the stop is the	ported by a sta	ainless steel tape, already		
	ND ELECT		HARACTERISTICS		
IECHANICAL	ECHANICAL		Cod. MTV	I	
Magnetic sensor with die-cast Possibility to fix the magnetic		ws or with	Pole pitch	2.54+2.54 mm	
through M3 screws. Wide alignment tolerances.			Reference indexes	C = constant step (every 2.54 mm)	
LECTRICAL			Resolution	up to 24,000 DPI **	
Very flexible power cable.Reading through positioning sensor based on magneto			Accuracy	± 10 µm ***	
resistance, with AMR effect (Magnetic Anisotropy).High signal stability.			Max. traversing speed	15 m/s	
Electrical protection against i and short circuits on output po		supply polarity	Max. frequency	6 kHz	
 For applications where the maximum speed exceeds 1 m/s, it is necessary to use a cable suitable for continuous movements. 					
CABLE:			Repeatability	± 1 increment	
As a standard, the sensor is s	••	•	A, B and I₀ output signals	sine wave 1 Vpp	
 8-wire shielded cable Ø = 6.1 mm, PVC external sheath, with low friction coefficient, oil resistant; 			Vibration resistance (EN 60068-2-6)	300 m/s ² [55 ÷ 2,000 Hz]	
 Conductors section: power supply 0.35 mm²; signals 0.14 mm². 			Shock resistance (EN 60068-2-27)	1,000 m/s ² (11 ms)	
UR cable or cable with reduced		han 60 mm	Protection class (EN 60529)	IP 67	
he cable's bending radius she	CONDUCT		Operating temperature	0 °C ÷ 50 °C	
SIGNALS	COLOR		Storage temperature	-20 °C ÷ 80 °C	
A	Green		Relative humidity	100%	
B	Ā Orange B White		Power supply	5 ÷ 28 Vdc ± 5%	
	Light-blue		Current consumption without load	90 mA _{MAX}	
B	Brown				
B I ₀	BIOWII		Current consumption with load	110 mA _{MAX} (with 5 V and R = 120 Ω)	
	Yellow			70 mA _{MAX} (with 28 V and R = 1.2 k Ω)	
l _o	-		Electrical connections	70 mA_{MAX} (with 28 V and R = 1.2 kΩ) see related table	
I ₀ T ₀	Yellow		Electrical connections		

** ***

Cable extensions need to have a 0.5 mm² section for power supply conductors. Depending on CNC division factor. To obtain the declared accuracy values, it is necessary to respect the alignment tolerances prescribed by the Manufacturer. Better accuracy can be obtained by reducing the gap between the sensor and the magnetic band.



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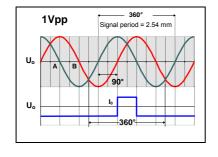
A and B amplitude

A and B phase displacement

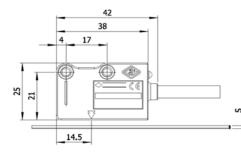
Reference voltage U₀

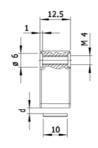
I₀ amplitude

OUTPUT SIGNALS



SENSOR DIMENSIONS





values in mm	MP254	MP254 + CV103	MP254 + SP202	MP254 + GVS 100
s	1.3	1.6	2.1	7.6
d	0.1 ÷ 1	0.7 _{MAX}	0.2 _{MAX}	N.A.
s = thickness				

0.6 Vpp ÷ 1.2 Vpp typical 1 Vpp

 $90^{\circ} \pm 10^{\circ}$ electrical

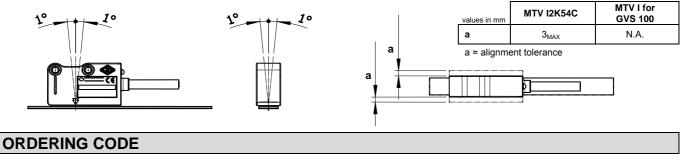
≈ 2.5 V

Signal amplitude is referred to a differential measurement made with 120 Ω impedance and a minimum power supply voltage of 5 V to the sensor.

0.25 V ÷ 0.6 V (usable component)

d = distance to be maintained between sensor and surface of the magnetic band (or eventual cover/support)

SENSOR ALIGNMENT TOLERANCES



MODEL	POLE PITCH	PERIOD	REFERENCE INDEXES	POWER SUPPLY	OUTPUT SIGNALS	CABLE	CONNECTION	SPECIAL
MTV	I	2K54	С	528V	S	M02 / N	SC	
	I = 2.54+2.54 mm	2K54 = 2.54 mm	C = constant step	528V = 5÷28 Vdc	S = sine wave	M01/N = 1 m M02/N = 2 m M03/N = 3 m	SC = without connector Cnn = progressive	No cod = standard SPnn = special nn

Example Car MAGNETIC SENSOR MTV I 2K54 C 528V S M02 / N SC